







CONSENSUM

<u>Communication and Sensing in Connected and Autonomous Vehicles'</u> Environment

Nowadays a vehicle is no more a collection of separated electronic control units for the actuators meant to respond to the driver actions in order to ensure a safe and comfortable ride. Users are looking forward for vehicles with high levels of automation, with advanced driver assistance systems (ADAS) transformed into connected and autonomous vehicles (CAV), and domain control units replaced by online upgradeable software defined cars, while maintaining users' safety and data security. To this end, the car needs to sense timely and reliably the environment. Be it that by means of camera, radar, lidar or other sensing technologies, the signal processing support is crucial for each and every of them. The information sensed is fused in order to complete ADAS functions or further complex tasks like trajectory planning and obstacle avoidance. Newest approaches imply artificial intelligence specific learning-based technologies. The car's "brain" thus requires more powerful computing resources not only to accommodate the newest processing techniques, but also to cope with the high quantity of collected information. In this context, topics of high interest include processing information received from sensors, neighbouring vehicles, and infrastructure or deferring when necessary part of processing and decision making elsewhere, e.g., in the edge or cloud. This is enabled by newest radio and communication technologies, such as precise radio localization, vehicular networking through V2X or low latency and high throughput reliable communication based on 5G technology.

Given the motivations above, the special session aims at presenting relevant solutions and results on sensing and communications technologies that may turn a network of vehicles and associated infrastructure into a cooperative reliable and precise perception and decision system that would enable automated mobility.

	Address:	ISSCS 2021 Secretariat Faculty of Electronics, Telecommunications and Information Technology Bd. Carol I, no.11, lasi, 700506 Romania
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Thu, 15.07.2021, 12:05-13:45 **CONSENSUM Special Session Papers** (Romania time) http://scs.etti.tuiasi.ro/isscs2021/technical_program.html#B1 Driver's warning notifications by using FM Florin Doru Hutu, Radu Gabriel Bozomitu **RDS** technology A Vision-Dynamics Learning Approach to Cosmin Ginerica, Sorin M. Grigorescu, **Prediction-Based Control in Autonomous** Dorian Cojocaru Vehicles **A Minimum Frequency Scheduler for** Florescu Roxana-Daniela, Puscasu Alexandru-Daniel, Giurgica Gabriel **Autonomous Driving Systems Application Design Principles for Road Users'** Andreea V. Militaru, Constantin F. Caruntu, Ciprian R. Comsa Safety **Automated Onboarding, Testing and Validation** Andreea Bonea, Cristian Patachia-Sultanoiu, Marius Iordache, Ioan Framework for NetApps Constantin, Andrei Radulescu, Ciprian R. Comsa, Constantin F. Caruntu

CONSENSUM Round Table		Thu, 15.07.2021, 18:30-20:00 (Romania time)		
http://scs.etti.tuiasi.ro/isscs2021/technical_program.html#glance				
Prof. Dr. Iulian CIOCOIU,	Moderators,			
Assoc. Prof. Ciprian COMSA	"Gheorghe As	achi" Technical University of Iasi		
Dr. Corina APACHITE	Head of He[a]	t Artificial Intelligence,		
	Continental A	utomotive – Frankfurt		
Dr. David WOON	Co-Director, C	Continental-NTU Corporate Lab,		
	Continental A	utomotive – Singapore –		
	talk on "Accel	erating AV research through		
	partnerships w	rith Governments and Universities"		
Dr. David GONZALEZ G.	Sr. Researcher	Wireless Communications,		
	Continental A	utomotive – Frankfurt		
Marius IORDACHE,	Architecture M	Manager,		
Cristian PATACHIA	Development a	and Innovation Manager,		
	Orange Romai	nia		
Prof. dr. Sorin GRIGORESCU	Head of Artific	cial Intelligence at Elektrobit		
	Automotive R	omania		
Dr. Sighard SCHRAEBLER	Researcher Ar	tificial Intelligence, Robotics and		
	Autonomous I	Oriving,		
	Continental A	utomotive – Frankfurt –		
	talk on "The A	Autonomy Stack"		

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